

# The Concurrent Composition of Differential Privacy

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## Outline

- Background
- Definitions and Basic Properties
- Concurrent Composition for Pure Interactive Differential Privacy
- Concurrent Composition for Approximate Interactive Differential Privacy
- Characterization of Concurrent Composition
- Empirical Findings & Future Work



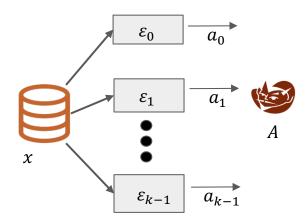
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## Background: DP under Composition



- Goal: analyze the privacy loss under the composition of multiple different mechanisms on the same dataset
  - Rarely want to release only a single statistic about a dataset.
  - Useful tool in algorithm design.
  - If the building blocks are proven to be private, it would be easy to reason about privacy of a complex algorithm built on these building blocks.



## Background: DP under Composition



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- Basic composition: If  $M_i$  is  $(\varepsilon, \delta)$  –DP for i = 0, ..., k 1, then  $M(x) = (M_0(x), ..., M_{k-1}(x))$  is  $(k\varepsilon, k\delta)$  –DP.
  - The randomness of  $M_i$  are independent to each other.
- Advanced composition: If  $M_i$  is  $(\varepsilon, \delta)$  –DP for i = 0, ..., k 1, then  $M(x) = (M_0(x), ..., M_{k-1}(x))$  is  $(O(\sqrt{k \log(\frac{1}{\delta'})} \varepsilon, k\delta + \delta')$ -DP.
  - The randomness of Mi are independent to each other.
- Optimal Composition [KOV15, MV16]
- Moment accountant [ACGMMTZ16]

#### **Interactive Differential Privacy**



- Many of the useful differential privacy primitives are actually interactive mechanisms, which allow one to ask an adaptive sequence of queries about the dataset.
  - e.g., Sparse Vector Technique (SVT) Many applications!

```
Input: q_1, ..., q_i, ..., q_{\infty}

If q_i + Noise > T<sub>i</sub> + Noise, output T;

else output \perp.

* c \neq number of \top (Privacy cost is proportional to \sqrt{c})

(Adapted from Yuging Zhu)
```

## Interactive DP under Composition



- There could be more than one composition operations for interactive mechanisms.
- **Sequential Composition**: all of the queries to the current mechanism must be completed before the interaction with another mechanism can be spawned.

• **Concurrent Composition**: multiple interactions can be spawned and be executed simultaneously, queries to the mechanisms can be arbitrarily interleaved.



#### Main Results



• Group Privacy-like bound  $(k\varepsilon, ke^{k\varepsilon}\delta)$  for the concurrent composition of approximate interactive DP mechanisms.

- Characterize arbitrary **pure** interactive DP mechanism as the interactive post-processing of randomized response (a non-interactive mechanism).
- => **Optimal bound** for the concurrent composition of pure interactive DP.
- Based on computer simulation, we conjecture that optimal composition bound may extend to approximate DP.



## Outline

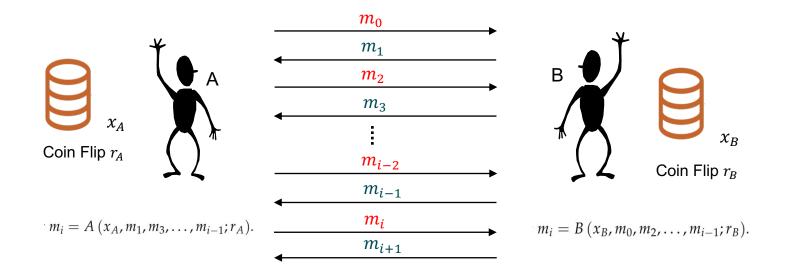
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#### Formalization: interactive protocol



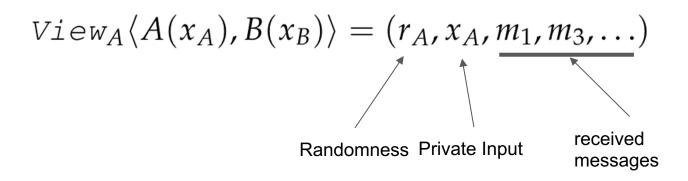
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- Interactive Protocol between two parties A and B
  - Each party as a function
  - (private input, received messages, random coins) => Next message to be sent out





## Formalization: view of a party



- In our case, party A is the adversary and party B is an interactive mechanism whose input is dataset x.
- Since we will only be interested in the adversary's view and the adversary does not have an input, we will drop the subscript and write A's view as View(A, B(x))

# Formalization: interactive differential privacy



• The interactive differentially privacy as a type of interactive protocol between an adversary (without any computational limitations) and an interactive mechanism of special properties.

**Definition 4** (Interactive Differential Privacy). A randomized algorithm  $\mathcal{M}$  is  $(\varepsilon, \delta)$ -differentially private interactive mechanism if for every pair of adjacent datasets x, x', for every adversary algorithm  $\mathcal{A}$ , for every possible output set  $T \subseteq \text{Range}(\forall i \in w \langle \mathcal{A}, \mathcal{M}(\cdot) \rangle)$  we have

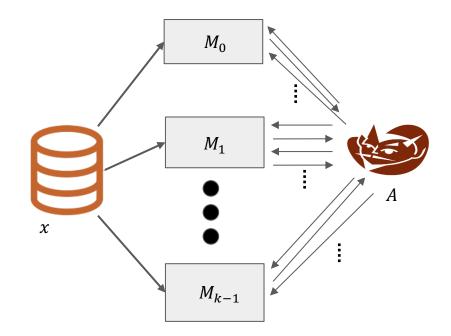
 $\Pr\left[\operatorname{View}\langle \mathcal{A}, \mathcal{M}(x)\rangle \in T\right] \leq e^{\varepsilon} \Pr\left[\operatorname{View}\langle \mathcal{A}, \mathcal{M}(x')\rangle \in T\right] + \delta$ 

#### **Concurrent Composition**



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• We use  $ConComp(M_0, ..., M_{k-1})$  to denote the concurrently composed mechanism of  $M_0, ..., M_{k-1}$ .

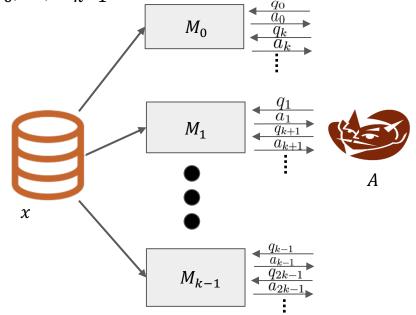


## **Ordered Concurrent Composition**



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• For the convenience of the proof, we introduce a variant of concurrent composition of interactive protocols, which only accept queries in the exact order of  $M_0, \ldots, M_{k-1}$ .

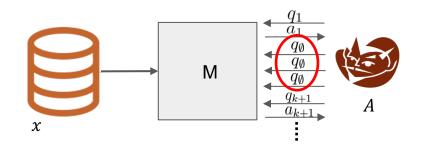


## **Ordered Concurrent Composition**



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• We also introduce the **null query extension** of an interactive mechanism, which has the exact same output distribution of the original mechanism but also accept "dummy" query strings.



## **Ordered Concurrent Composition**



- Lemma: to prove ConComp(M<sub>0</sub>, ..., M<sub>k-1</sub>) is (ε, δ)-DP, it suffices to prove the ordered concurrent composition of null query extensions of these mechanisms is also (ε, δ)-DP.
  - Intuition: if the first query is sent to  $M_i$ , the second query is not sent to  $M_{i+1}$  but  $M_j$ , we can simply fill in dummy queries between  $M_i$  and  $M_j$ .
- => We always assume the queries  $q_0, ..., q_{k-1}, q_k, ..., q_{\{2k-1\}}, ...$  from adversary are sent to  $M_0, ..., M_{k-1}$  in order in the proof, i.e.,  $q_\ell$  is sent to  $M_{\ell \mod k}$ .
  - If an adversary A is concurrently interacting with two mechanisms  $M_0, M_1$ , we assume the queries **alternates** between them.



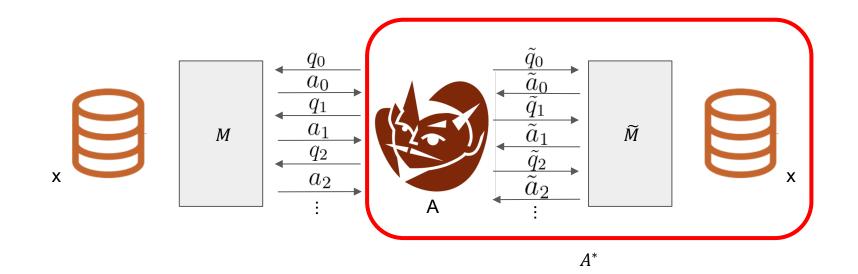
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## Concurrent Composition of Pure Interactive Differential Privacy

• Proof Sketch: view A and M as a combined adversary  $A^*$  interacting with  $\widetilde{M}$ 





# Concurrent Composition of Pure Interactive Differential Privacy

- Proof Sketch: view A and M as a combined adversary  $A^*$  interacting with  $\widetilde{M}$ 
  - $A^*$  is a well-defined strategy throughout the entire interactive session with M
    - Randomness of  $A^*$ : the randomness of A and  $\widetilde{M}$
    - Next-query function is also naturally defined:
      - 1. Random coin tosses for  $\mathcal{A}^*_{\tilde{\mathcal{M}}}(x)$  consist of  $r = (r_{\mathcal{A}}, r_{\tilde{\mathcal{M}}})$ .
      - 2.  $\mathcal{A}^*_{\tilde{\mathcal{M}}}(x)(a_0, a_1, \dots, a_{i-1}; r)$  is computed as follows:
        - (a)  $\tilde{q}_{i-1} = \mathcal{A}(a_0, \tilde{a}_0, \dots, a_{i-1}; r_{\mathcal{A}})$ , send to  $\tilde{\mathcal{M}}$ .
        - (b)  $\tilde{a}_{i-1} = \tilde{\mathcal{M}}(x, \tilde{q}_0, \tilde{q}_1, \dots, \tilde{q}_{i-1}; r_{\tilde{\mathcal{M}}})$ , send to  $\mathcal{A}$ .
        - (c)  $q_i = \mathcal{A}(a_0, \tilde{a}_0, \ldots, a_{i-1}, \tilde{a}_{i-1}; r_{\mathcal{A}}).$
        - (d) Output  $q_i$ .



## Concurrent Composition of Pure Interactive Differential Privacy

- Proof Sketch: view A and M as a combined adversary  $A^*$  interacting with  $\widetilde{M}$ 
  - Given a transcript of  $A^*$ 's view, we can recover the view of A through postprocessing, which is formulated as follows:

Post  $(r_{\mathcal{A}}, r_{\tilde{\mathcal{M}}}, a_0, a_1, \dots, a_{T-1}; \mathcal{A}, \tilde{\mathcal{M}}(x))$ :

1. For i = 1 ... T - 1, compute

(a)  $\tilde{q}_{i-1} = \mathcal{A}(a_0, \tilde{a}_0, \dots, a_{i-1}; r_{\mathcal{A}})$ 

- (b)  $\tilde{a}_{i-1} = \tilde{\mathcal{M}}(x, \tilde{q}_1, \tilde{q}_2, \dots, \tilde{q}_{i-1}; r_{\tilde{\mathcal{M}}})$
- 2. Output  $(r_A, a_0, \tilde{a}_0, \ldots, a_{T-1}, \tilde{a}_{T-1})$ .



## Concurrent Composition of Pure Interactive Differential Privacy

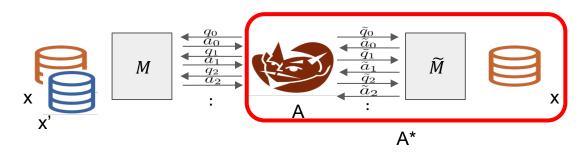
- Proof Sketch: view A and M as a combined adversary  $A^*$  interacting with  $\widetilde{M}$ 
  - Given a transcript of  $A^*$ 's view, we can recover the view of A through post-processing.
  - For any event *T*, the probability that *A*'s view is in *T* is exactly equal to the probability that  $A^*$ 's view is in the inverse of the post-processing algorithm of event *T*.

 $\Pr\left[\operatorname{View}\langle\mathcal{A},\operatorname{ConComp}(\mathcal{M}(x),\tilde{\mathcal{M}}(x))\rangle\in T\right]=\Pr\left[\operatorname{View}\langle\mathcal{A}_{\tilde{\mathcal{M}}}^*(x),\mathcal{M}(x)\rangle\in\operatorname{Post}^{-1}(T)\right]$ 



# Concurrent Composition of Pure Interactive Differential Privacy

- Proof Sketch: view A and M as a combined adversary  $A^*$  interacting with  $\widetilde{M}$ 
  - Given a transcript of  $A^*$ 's view, we can recover the view of A through post-processing.
  - For any event *T*, the probability that *A*'s view is in *T* is exactly equal to the probability that  $A^*$ 's view is in the inverse of the post-processing algorithm of event *T*.
  - The random variable of  $A^*$ 's view enjoys differential privacy guarantee.





## Concurrent Composition of Pure Interactive Differential Privacy

 We say two random variables X and X' are (ε, δ)-indistinguishable if for every event T we have

 $\Pr[X \in T] \le e^{\varepsilon} \cdot \Pr[X' \in T] + \delta$  $\Pr[X' \in T] \le e^{\varepsilon} \cdot \Pr[X \in T] + \delta$ 

- Denote as  $X \stackrel{(\epsilon,\delta)}{\approx} X'$
- Simple property: if  $X \stackrel{(\epsilon,0)}{\approx} X'$ , and  $X' \stackrel{(\tilde{\epsilon},0)}{\approx} X''$ , then  $X \stackrel{(\epsilon+\tilde{\epsilon},0)}{\approx} X''$



## Concurrent Composition of Pure Interactive Differential Privacy

- Suppose *M* is  $(\varepsilon, 0)$ -DP,  $\widetilde{M}$  is  $(\widetilde{\varepsilon}, 0)$ -DP
- We know that  $View(A^*_{\tilde{M}(x)}, M(x))$  and  $View(A^*_{\tilde{M}(x)}, M(x'))$  are  $(\varepsilon, 0)$ -indistinguishable.
- =>  $View(A, ConComp(M(x), \tilde{M}(x)))$  and  $View(A, ConComp(M(x'), \tilde{M}(x)))$  are  $(\varepsilon, 0)$ -indistinguishable.
- Symmetrically, we have  $\operatorname{View}(A, \operatorname{ConComp}(M(x'), \tilde{M}(x))) \stackrel{(\tilde{\varepsilon}, 0)}{\approx} \operatorname{View}(A, \operatorname{ConComp}(M(x'), \tilde{M}(x')))$
- Finally, we can bound the privacy of A's view in the concurrent composition when the underlying dataset is x vs x'.

 $\mathtt{View}(A, \mathrm{ConComp}(M(x), \tilde{M}(x))) \overset{(\varepsilon + \tilde{\varepsilon}, 0)}{\approx} \mathtt{View}(A, \mathrm{ConComp}(M(x'), \tilde{M}(x')))$ 



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## Concurrent Composition of Approximate Interactive Differential Privacy

- Suppose interactive mechanisms  $M_0, ..., M_{\{k-1\}}$  are each  $(\epsilon_i, \delta_i)$ -differentially private.
- View *A* and *M*<sub>0</sub>, ..., *M*<sub>{*i*-1}</sub>, *M*<sub>{*i*+1}</sub>, ..., *M*<sub>{*k*-1}</sub> as a combined adversary *A*<sup>\*</sup>, we can show that:

 $\Pr\left[\operatorname{View}\langle\mathcal{A}, \operatorname{ConComp}(\mathcal{M}_0(x'), \dots, \mathcal{M}_{i-1}(x'), \mathcal{M}_i(x), \dots, \mathcal{M}_{k-1}(x))\rangle \in S\right]$  $\leq e^{\varepsilon_i} \Pr\left[\operatorname{View}\langle\mathcal{A}, \operatorname{ConComp}(\mathcal{M}_0(x'), \dots, \mathcal{M}_{i-1}(x'), \mathcal{M}_i(x'), \dots, \mathcal{M}_{k-1}(x))\rangle \in S\right] + \delta_i$ 

#### Group Privacy-like Bound



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 $\Pr[\text{View}(\mathcal{A}, \text{ConComp}(\mathcal{M}_0(x), \mathcal{M}_1(x), \dots, \mathcal{M}_{k-1}(x))) \in S]$  $\leq e^{\varepsilon_0} \Pr\left[ \text{View}\langle \mathcal{A}, \text{ConComp}(\mathcal{M}_0(x'), \mathcal{M}_1(x), \dots, \mathcal{M}_{k-1}(x)) \rangle \in S \right] + \delta_0$  $< e^{\varepsilon_0}(e^{\varepsilon_1} \Pr\left[ \forall i \in W \langle \mathcal{A}, \operatorname{ConComp}(\mathcal{M}_0(x'), \mathcal{M}_1(x'), \dots, \mathcal{M}_{k-1}(x)) \rangle \in S \right] + \delta_1) + \delta_0$ < . . .  $< e^{\sum_{i=0}^{k-1} \varepsilon_i} \Pr\left[ \text{View} \langle \mathcal{A}, \text{ConComp}(\mathcal{M}_0(x'), \mathcal{M}_1(x'), \dots, \mathcal{M}_{k-1}(x')) 
angle \in S 
ight]$  $+ (\delta_0 + e^{\varepsilon_0} \delta_1 + e^{\varepsilon_0 + \varepsilon_1} \delta_2 + \ldots + e^{\sum_{i=0}^{k-2} \varepsilon_i} \delta_{k-1}) \leq k e^{\sum_{i=0}^{k-1} \varepsilon_i} \max_i (\delta_i)$  $=\left(1+e^{arepsilon}+e^{2arepsilon}+\cdots+e^{(k-1)\cdotarepsilon}
ight)\cdot\delta$  Same bound for Group Privacy Group Privacy-like Bound



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• Randomized Response

 $\mathrm{RR}_{(\varepsilon,\delta)}: \{0,1\} \to \{0,1, \text{'} \texttt{Iam0'}, \text{'} \texttt{Iam1'}\} \text{ is } (\varepsilon,\delta)\text{-}\mathsf{DP}$ 

$$\begin{aligned} &\Pr\left[\mathrm{RR}_{(\varepsilon,\delta)}(0) = \operatorname{Iam0'}\right] = \delta & \Pr\left[\mathrm{RR}_{(\varepsilon,\delta)}(1) = \operatorname{Iam0'}\right] = 0 \\ &\Pr\left[\mathrm{RR}_{(\varepsilon,\delta)}(0) = 0\right] = (1-\delta) \cdot \frac{e^{\varepsilon}}{1+e^{\varepsilon}} & \Pr\left[\mathrm{RR}_{(\varepsilon,\delta)}(1) = 0\right] = (1-\delta) \cdot \frac{1}{1+e^{\varepsilon}} \\ &\Pr\left[\mathrm{RR}_{(\varepsilon,\delta)}(0) = 1\right] = (1-\delta) \cdot \frac{1}{1+e^{\varepsilon}} & \Pr\left[\mathrm{RR}_{(\varepsilon,\delta)}(1) = 1\right] = (1-\delta) \cdot \frac{e^{\varepsilon}}{1+e^{\varepsilon}} \\ &\Pr\left[\mathrm{RR}_{(\varepsilon,\delta)}(0) = \operatorname{Iam1'}\right] = 0 & \Pr\left[\mathrm{RR}_{(\varepsilon,\delta)}(1) = \operatorname{Iam1'}\right] = \delta \end{aligned}$$

[KOV15, MV17]

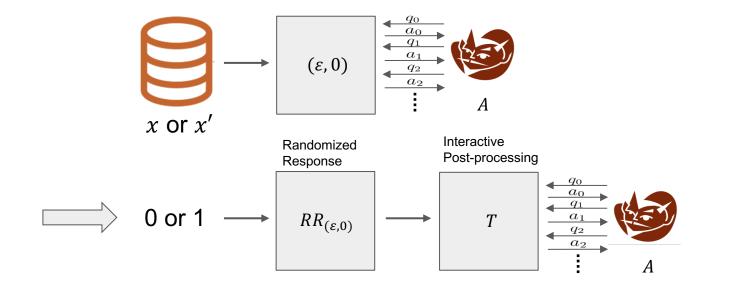


- For every non-interactive  $(\varepsilon, \delta)$  –DP algorithms and every neighboring dataset  $x_0 \sim x_1$ , there exists a post-processing *T* of randomized response  $RR_{(\varepsilon,\delta)}$  such that  $T(RR_{(\varepsilon,\delta)}(b))$  is identically distributed to  $M(x_b)$  [KOV15, MV17].
- Post-processing preserves differential privacy
   >To analyze the composition of arbitrary non-interactive DP algorithms, it suffices to analyze the composition of *RR*'s.
- If we are able to prove a similar result for interactive differential privacy, then we will be able to extend all results of composition theorem for non-interactive mechanisms to interactive mechanisms!



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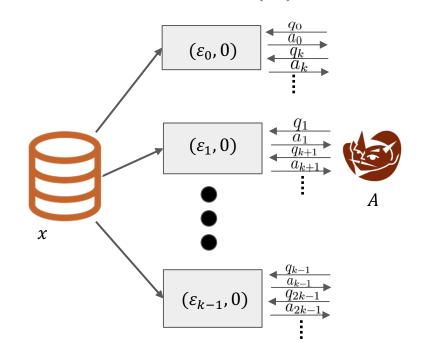
• **Every** interactive  $(\varepsilon, 0)$  –DP mechanisms can be simulated as the postprocessing of randomized response  $RR_{(\varepsilon,0)}$ .





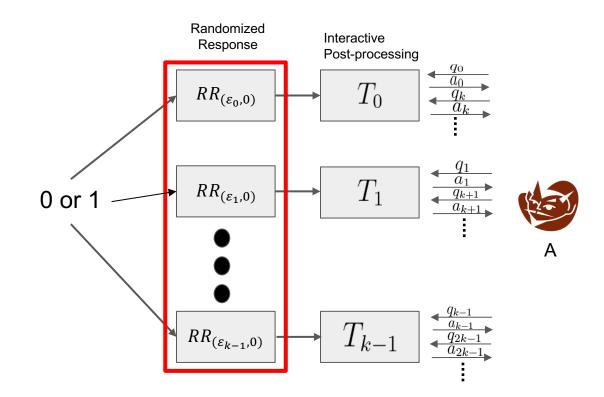
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• **Every** interactive  $(\varepsilon, 0)$  –DP mechanisms can be simulated as the postprocessing of randomized response  $RR_{(\varepsilon,0)}$ .





# Characterization of Concurrent Composition





If interactive mechanism M<sub>0</sub>, ..., M<sub>k-1</sub> are each (ε<sub>i</sub>, 0)-DP for i = 0..k - 1, then given a target δ<sub>g</sub>, the privacy parameter of the current composition
 ConComp(M<sub>0</sub>, ..., M<sub>k-1</sub>) is tightly upper bounded by the least value of ε<sub>g</sub> such that

$$\frac{1}{\prod_{i=0}^{k-1} (1+\mathrm{e}^{\varepsilon_i})} \sum_{S \subseteq \{0,...,k-1\}} \max\left\{\mathrm{e}^{\sum_{i \in S} \varepsilon_i} - \mathrm{e}^{\varepsilon_g} \cdot \mathrm{e}^{\sum_{i \notin S} \varepsilon_i}, 0\right\} \leq \delta_g$$

(Optimal Bound from MV17 for non-interactive DP)



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## **Empirical Findings & Future Work**



- We find empirical evidence supports that the Optimal Composition Theorems from [KOV15] can be extended to the concurrent composition of approximate DP mechanisms.
  - We evaluate whether any 2-round  $(\epsilon, \delta)$  interactive mechanisms with 1-bit messages can be simulated by some interactive post-processing of randomized response.

